

Selected Exercises for the Feynman Lectures on Physics by Richard Feynman, Et Al. Chapter 4 Kinematics – Detailed Work by James Pate Williams, Jr. BA, BS, MSwE, PhD

4.1

(a)

$$\ddot{x}(t) = a$$

$$\int_{v_{x_0}}^{v_x} dv = v_x(t) - v_{x_0} = a \int_0^t d\tau = at$$

$$v_x(t) = v_{x_0} + at$$

$$\int_{x_0}^x d\xi = x - x_0 = v_{x_0} \int_0^t d\tau + a_x \int_0^t d\tau = v_{x_0}t + \frac{1}{2}at^2$$

$$x(t) = x_0 + v_{x_0}t + \frac{1}{2}at^2$$

(b)

$$t = \frac{v_x - v_{x_0}}{a}$$

$$x(t) = x_0 + v_{x_0} \left(\frac{v_x - v_{x_0}}{a} \right) + \frac{1}{2}a \left(\frac{v_x - v_{x_0}}{a} \right)^2 = x_0 + \frac{v_x v_{x_0} - v_{x_0}^2}{a} + \frac{1}{2}a \left(\frac{v_x^2 - 2v_x v_{x_0} + v_{x_0}^2}{a^2} \right)$$

$$a(x - x_0) = \frac{1}{2}v_x^2 - \frac{1}{2}v_{x_0}^2$$

$$2a(x - x_0) = v_x^2 - v_{x_0}^2$$

$$v_x^2 = v_{x_0}^2 + 2a(x - x_0)$$

4.2

(a)

$$\ddot{x}(t) = a_x$$

$$\ddot{y}(t) = a_y$$

$$\ddot{z}(t) = a_z$$

$$\int_{v_{x_0}}^{v_x} dv = v_x(t) - v_{x_0} = a_x \int_0^t d\tau = a_x t$$

$$\int_{v_{y_0}}^{v_y} dv = v_y(t) - v_{y_0} = a_y \int_0^t d\tau = a_y t$$

$$\int_{v_{z_0}}^{v_z} dv = v_z(t) - v_{z_0} = a_z \int_0^t d\tau = a_z t$$

$$v_x(t) = v_{x_0} + a_x t$$

$$v_y(t) = v_{y_0} + a_y t$$

$$v_z(t) = v_{z_0} + a_z t$$

$$\int_{x_0}^x d\xi = x - x_0 = v_{x_0} \int_0^t d\tau + a_x \int_0^t d\tau = v_{x_0} t + \frac{1}{2} a_x t^2$$

$$\int_{y_0}^y d\eta = y - y_0 = v_{y_0} \int_0^t d\tau + a_y \int_0^t d\tau = v_{y_0} t + \frac{1}{2} a_y t^2$$

$$\int_{z_0}^z d\zeta = z - z_0 = v_{z_0} \int_0^t d\tau + a_z \int_0^t d\tau = v_{z_0} t + \frac{1}{2} a_z t^2$$

$$x(t) = x_0 + v_{x_0} t + \frac{1}{2} a_x t^2$$

$$y(t) = y_0 + v_{y_0} t + \frac{1}{2} a_y t^2$$

$$z(t) = z_0 + v_{z_0} t + \frac{1}{2} a_z t^2$$

(b)

$$x(t) = x_0 + v_{x_0} \left(\frac{v_x - v_{x_0}}{a_x} \right) + \frac{1}{2} a_x \left(\frac{v_x - v_{x_0}}{a_x} \right)^2 = x_0 + \frac{v_x v_{x_0} - v_{x_0}^2}{a_x} + \frac{1}{2} a_x \left(\frac{v_x^2 - 2v_x v_{x_0} + v_{x_0}^2}{a_x^2} \right)$$

$$a_x(x - x_0) = \frac{1}{2}v_x^2 - \frac{1}{2}v_{x_0}^2$$

$$2a_x(x - x_0) = v_x^2 - v_{x_0}^2$$

$$v_x^2 = v_{x_0}^2 + 2a_x(x - x_0)$$

$$y(t) = y_0 + v_{y_0} \left(\frac{v_y - v_{y_0}}{a_y} \right) + \frac{1}{2} a_y \left(\frac{v_y - v_{y_0}}{a_y} \right)^2 = y_0 + \frac{v_y v_{y_0} - v_{y_0}^2}{a_y} + \frac{1}{2} a_y \left(\frac{v_y^2 - 2v_y v_{y_0} + v_{y_0}^2}{a_y^2} \right)$$

$$a_y(y - y_0) = \frac{1}{2}v_y^2 - \frac{1}{2}v_{y_0}^2$$

$$2a_y(y - y_0) = v_y^2 - v_{y_0}^2$$

$$v_y^2 = v_{y_0}^2 + 2a_y(y - y_0)$$

$$z(t) = z_0 + v_{z_0} \left(\frac{v_z - v_{z_0}}{a_z} \right) + \frac{1}{2} a_z \left(\frac{v_z - v_{z_0}}{a_z} \right)^2 = z_0 + \frac{v_z v_{z_0} - v_{z_0}^2}{a_z} + \frac{1}{2} a_z \left(\frac{v_z^2 - 2v_z v_{z_0} + v_{z_0}^2}{a_z^2} \right)$$

$$a_z(z - z_0) = \frac{1}{2}v_z^2 - \frac{1}{2}v_{z_0}^2$$

$$2a_z(z - z_0) = v_z^2 - v_{z_0}^2$$

$$v_z^2 = v_{z_0}^2 + 2a_z(z - z_0)$$

4.3

(a)

$$\theta = \frac{s}{R} \approx \frac{R \sin \theta}{R} = \sin \theta \quad \forall \theta \ll 1$$

$$e^{\pm i\theta} = \cos \theta \pm i \sin \theta$$

$$e^{i\theta} e^{-i\theta} = e^0 = 1 = (\cos \theta + i \sin \theta)(\cos \theta - i \sin \theta) = \cos^2 \theta - i^2 \sin^2 \theta = \cos^2 \theta + \sin^2 \theta$$

$$\begin{aligned} e^{i(\theta \pm \phi)} &= \cos(\theta \pm \phi) + i \sin(\theta \pm \phi) = e^{i\theta} e^{\pm i\phi} = (\cos \theta + i \sin \theta)(\cos \phi \pm i \sin \phi) \\ &= \cos \theta \cos \phi \pm i^2 \sin \theta \sin \phi + i(\sin \theta \cos \phi \pm \cos \theta \sin \phi) \end{aligned}$$

$$\cos(\theta \pm \phi) = \cos \theta \cos \phi \mp \sin \theta \sin \phi$$

$$\sin(\theta \pm \phi) = \sin \theta \cos \phi \pm \cos \theta \sin \phi$$

$$\sin \theta \approx \theta$$

$$\cos \theta = 1 - \sin^2 \theta \approx 1 - \theta^2 \approx 1$$

$$\frac{dy}{dx} = \lim_{\Delta x \rightarrow 0} \frac{y(x + \Delta x) - y(x)}{\Delta x}$$

$$y(x) = \sin(x)$$

$$\begin{aligned}
\frac{dy}{dx} &= \lim_{\Delta x \rightarrow 0} \frac{\sin(x + \Delta x) - \sin(x)}{\Delta x} = \lim_{\Delta x \rightarrow 0} \frac{\sin(x) \cos(\Delta x) + \cos(x) \sin(\Delta x) - \sin(x)}{\Delta x} \\
&= \lim_{\Delta x \rightarrow 0} \frac{\sin(x) \cos(\Delta x) - \sin(x)}{\Delta x} + \lim_{\Delta x \rightarrow 0} \frac{\cos(x) \sin(\Delta x)}{\Delta x} \\
&= \lim_{\Delta x \rightarrow 0} \frac{\sin(x) - \sin(x)}{\Delta x} + \lim_{\Delta x \rightarrow 0} \frac{\cos(x) \Delta x}{\Delta x} = 0 + \cos(x) = \cos(x) \\
y(x) &= \cos(x)
\end{aligned}$$

$$\begin{aligned}
\frac{dy}{dx} &= \lim_{\Delta x \rightarrow 0} \frac{\cos(x + \Delta x) - \cos(x)}{\Delta x} = \lim_{\Delta x \rightarrow 0} \frac{\cos(x) \cos(\Delta x) - \sin(x) \sin(\Delta x) - \cos(x)}{\Delta x} \\
&= \lim_{\Delta x \rightarrow 0} \frac{\cos(x) - \sin(x) \Delta x - \cos(x)}{\Delta x} = \lim_{\Delta x \rightarrow 0} \frac{\cos(x) - \cos(x)}{\Delta x} + \lim_{\Delta x \rightarrow 0} \frac{-\sin(x) \Delta x}{\Delta x} \\
&= -\sin(x)
\end{aligned}$$

4.4

(a)

$$\theta = \omega t = \frac{Vt}{R}$$

$$x = R \cos \theta = R \cos \omega t$$

$$y = R \sin \theta = R \sin \omega t$$

$$v_x = \frac{dx}{dt} = -R\omega \sin \omega t = -V \sin \omega t$$

$$v_y = \frac{dy}{dt} = R\omega \cos \omega t = V \cos \omega t$$

$$a_x = \ddot{x} = \frac{dv_x}{dt} = -R\omega^2 \cos \omega t = -\frac{V^2}{R} \cos \omega t$$

$$a_y = \ddot{y} = \frac{dv_y}{dt} = -R\omega^2 \sin \omega t = -\frac{V^2}{R} \sin \omega t$$

$$a^2 = \sqrt{a_x^2 + a_y^2} = \sqrt{\left(\frac{V^2}{R}\right)^2} = \frac{V^2}{R}$$

Since

$$\cos^2 \theta + \sin^2 \theta = 1$$

(b)

$$a_x + \omega^2 x = \ddot{x} + \omega^2 x = -R\omega^2 \cos \omega t + R\omega^2 \cos \omega t = 0$$

$$a_y + \omega^2 y = \ddot{y} + \omega^2 y = -R\omega^2 \sin \omega t + R\omega^2 \sin \omega t = 0$$

4.5

$$v_{y_0} = 1000 \text{ ft min}^{-1}$$

$$a_y = \ddot{y} = \frac{dv_y}{dt} = -g = -32.174 \text{ ft sec}^{-2} = -32.174 \cdot 3600 \text{ ft min}^{-2}$$

$$a_y = -115830 \text{ ft min}^{-2}$$

$$v_y = -gt + v_{y_0}$$

$$y = -\frac{1}{2}gt^2 - v_{y_0}t + y_0$$

$$y_0 = 30000 \text{ ft}$$

$$y = 0$$

$$t = \frac{-v_{y_0} \pm \sqrt{v_{y_0}^2 + 2gy_0}}{-g} = \frac{-1000 \pm \sqrt{10^6 + 2 \cdot 1115830 \cdot 30000}}{-115830} = \frac{-1000 \pm 1711.85}{-115830}$$

$$t \approx 0.720 \text{ min} = 43.2 \text{ sec}$$

The time the balloon is in the air:

$$T = 1800 \text{ sec} + 43.2 \text{ sec} = 1843.2 \text{ sec}$$

$$v_y = -32.174 \cdot 43.2 \text{ ft sec}^{-1} + 0 \text{ ft sec}^{-1} = -1390 \text{ ft sec}^{-1}$$

4.6

$$x = x_0 + v_{x_0}t_x + \frac{1}{2}a_xt_x^2 = \frac{1}{2}a_xt_x^2$$

$$y = y_0 + v_{y_0}t_y + \frac{1}{2}a_yt_y^2$$

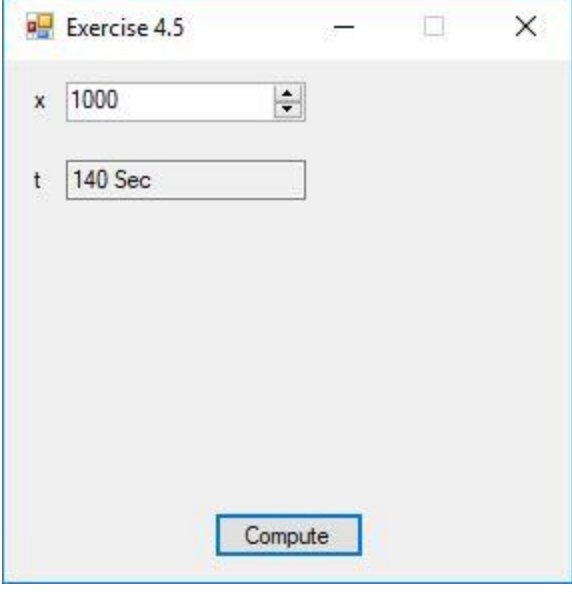
$$y_0 = x = \frac{1}{2}a_xt_x^2$$

$$v_{y_0} = a_xt_x$$

$$a_x = 20 \text{ cm sec}^{-2} = 0.20 \text{ m sec}^{-2}$$

$$a_y = -100 \text{ cm sec}^{-2} = -1.0 \text{ m sec}^{-2}$$

$$x + y = 2 \text{ km} = 2000 \text{ m}$$

A dialog box titled "Exercise 4.5" with a standard Windows window frame. It contains two input fields: "x" with the value "1000" and "t" with the value "140 Sec". A "Compute" button is located at the bottom right.

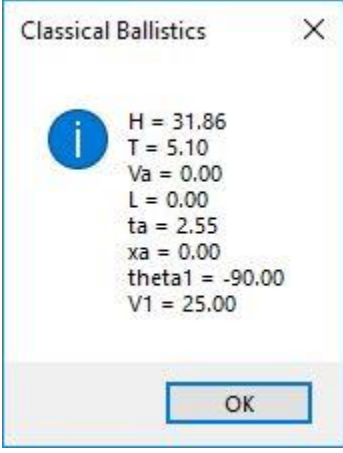
Exercise 4.5

x 1000

t 140 Sec

Compute

4.7

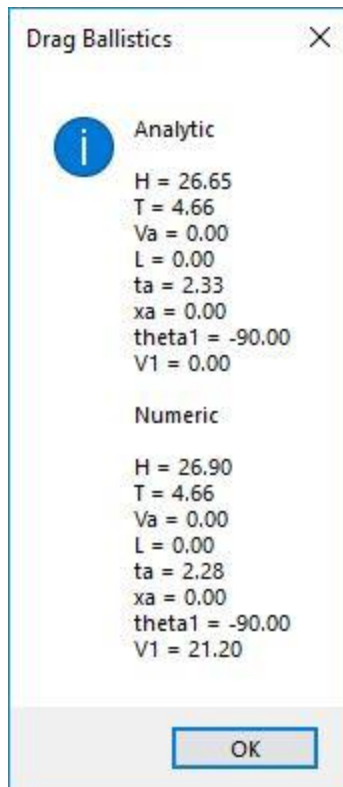
A dialog box titled "Classical Ballistics" with a standard Windows window frame. It displays a list of calculated values next to an information icon. An "OK" button is at the bottom right.

Classical Ballistics

H = 31.86
T = 5.10
Va = 0.00
L = 0.00
ta = 2.55
xa = 0.00
theta1 = -90.00
V1 = 25.00

OK

The velocity of 25 meters per second is approximately 56 miles per hour. We use a velocity squared retardation function:



The analytic solution is not valid for $\theta_0 = 90$ degrees. The numeric shows a time to apogee of 2.28 seconds and time of flight 4.66 seconds. The difference is $4.66 - 2.28$ seconds = 2.38 seconds so the time to return from apogee is greater than the time to reach apogee.