# A Modern Reincarnation of Ordnance Pamphlet 770 October 1941 by James Pate Williams, Jr. (jamespate@mac.com) 

## Abstract

This paper is dedicated to the effort of reproducing the first seven columns of United States Naval Ordnance Pamphlet 770 October 1941 using the exterior ballistics of the time, but on a modern digital computer. It should be well known that digital computers did not exist in 1941 and only electromechanical analog computers were available in that time frame. The pamphlet references "Exterior Ballistics 1935" by Lieutenant Commander Ernest Edward Herrmann of the United States Naval Academy so we rely heavily on this textbook. Exterior ballistics deals with the trajectory of a projectile after it leaves the barrel of the rifle. Interior ballistics is concerned with the dynamics of a projectile in the barrel of the gun.

## Introduction

Ordnance Pamphlet 770 October 1941 [1] gives a range table for the 16 - Inch/50 caliber naval artillery rifle that was used on the lowa class of fast battleships. The projectile had a weight of 2700 pounds, an initial velocity in a new gun of 2500 feet per second, length of 4.5 calibers, and a radius of ogive of 9.0 calibers. It is to be noted that 4.5 / $9=0.5$ and this number is the coefficient of form that we use in most of our ballistic calculations. According to Explanatory Note 5 of the document, the weather conditions to be assumed for the range table calculations are a density of $1.2034 \mathrm{~kg} / \mathrm{m}^{\wedge} 3$ corresponding to a temperature of 59 degrees Fahrenheit, a barometric pressure of 29.53 inches Mercury $(\mathrm{Hg})$, and a humidity of $78 \%$.

As stated in Explanatory Note 14 of the pamphlet the firings upon which the range table is based are given in a table consisting of the number of rounds, angle of elevation, initial velocity, range, mean error, and pattern. All the range related data are in yards. We make extensive use of this data.

The range table of the pamphlet consists of nineteen columns, but we are just interested in the primary first seven columns. The columns are the range in yards, the angle of elevation in degrees and minutes, the angle of fall (obliquity) in degrees and minutes, the time of flight in seconds, the striking velocity in feet per second, the drift in yards, and the maximum y-ordinate also called the height at apogee or summit. It is surmised that the main cause of drift is the gyroscopic action of the projectile.

As was stated in the abstract no digital computers existed at the time of the writing of the pamphlet. The Harvard Mark I electromechanical analog computer was not running until 1944. Grace Hopper worked on the Harvard Mark I for the U.S. Navy Bureau of Ships [2] during the war years. The U.S. Navy did have the Ford Mark I Fire Control Computer (FCC) in the 1930s and 1940s [3]. The FCC was a very sophisticated electromechanical analog computer (calculator) that worked via cams, gears, differentials, motors, etc. A manual for the Ford Mark I can be found on the website [4]. The Ford Mark I cost astounding \$75,000 U.S. dollars in 1945 which is $\$ 1,017,269.66$ in 2017 U.S. dollars.

This paper consists of four more sections. The first section explains the theoretical foundations of the experimental computations, the second section describes our computer application, the third section gives our experimental results, and finally, a conclusions section wraps up the paper.

## Theoretical Foundations

All the theory in our actual calculations comes from the United States Naval Academy undergraduate textbook "Exterior Ballistics 1935" [5]. The system of ordinary non-linear differential equations to be solved are given in Equations (601) to (606) in [5] which for clarity are reproduced in this paper below.

$$
\begin{gathered}
E=\frac{G_{v} \times H_{y}}{C} \\
x^{\prime \prime}=-E \cos \theta \\
y^{\prime \prime}=-E \sin \theta-g \\
x^{\prime}=v \cos \theta \\
y^{\prime}=v \sin \theta \\
v=\sqrt{\left(x^{\prime}\right)^{2}+\left(y^{\prime}\right)^{2}}
\end{gathered}
$$

The velocity dependent G function above is the Mayevski extensions of the Gavre functions. The H function is a height dependent ballistic density function. Both functions are found in Equations (403) and (405) of [6], and are restated here.

$$
\begin{gathered}
R_{a}=\frac{A_{1}}{C} v^{1.55}, \log A_{1}=7.60905-10,2600<v \leq 3600 \\
R_{a}=\frac{A_{2}}{C} v^{1.7}, \log A_{2}=7.09620-10,1800<v \leq 2600 \\
R_{a}=\frac{A_{3}}{C} v^{2}, \log A_{3}=6.11926-10,1370<v \leq 1800 \\
R_{a}=\frac{A_{4}}{C} v^{3}, \log A_{4}=2.98090-10,1230<v \leq 1370 \\
R_{a}=\frac{A_{5}}{C} v^{5}, \log A_{5}=6.80187-10,970<v \leq 1230 \\
R_{a}=\frac{A_{6}}{C} v^{3}, \log A_{6}=2.77344-10,790<v \leq 970 \\
R_{a}=\frac{A_{7}}{C} v^{2}, \log A_{7}=5.66989-10,0<v \leq 790 \\
G_{v}=C R_{a} \\
H_{y}=10^{-0.00001372 y}
\end{gathered}
$$

The $C$ in the $E$ equation is the ballistic coefficient defined by Equation (406) in [6] and is repeated for the benefit of the reader here:

$$
C=\frac{w}{\delta i d^{2}}
$$

Where $w$ is the weight in pounds which is 2700 pounds in our case, delta is the ratio of the density of the humid air to the standard density of $1.2034 \mathrm{~kg} / \mathrm{m}^{\wedge} 3, \mathrm{i}$ is the coefficient of form which we use 0.5 in most cases, and d is the diameter of the projectile in our case 16 inches.

We solve the ordinary differential equations using the Runge-Kutta fifth-order method code found in the treatise [7]. We translated the excellent C code from C to C\#. Incidentally, the C code was translated from an Algol scientific computing library. Also for angles of elevation less than 10 degrees we use Siacci's Method as described in [8].

## The Computer Application

The application was written in C\# on a personal computer using Windows Forms. The Microsoft Visual Studio 2015 integrated development environment was utilized. C\# is a modern strongly typed object oriented computer language. It is based on the venerable class of $C$ computer languages which includes C, C\#, C++, and Java.

The application consists at the time of this writing of six forms and thirteen non-form classes. The nonform classes are composed of around 3,000 lines of code and comments. The basic form is menu driven. The following two pictures illustrate the opening form and a range table generating form.


Figure 1 Main Application Form
The main application's Options Menu currently has three options: the determination of the optimal coefficients of form to be used in one of the range table generator functions, range table generation suing the Runge-Kutta firth-order numerical integration method, and range table generator using Siacci's method. The coefficients of for are found using an evolutionary hill-climber designed and implemented by the current author.

| 煰 Range Table Generator Runge-Kutta Fifth Order |  |  |  | - | $\times$ |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Theta0 (Degrees) | 0.000 | $\stackrel{\square}{*}$ | Trunnion Height (Feet) | 0 | $\stackrel{+}{*}$ |
| Theta1 (Degrees) | 1.000 | $\checkmark$ | Target Height (Feet) | 0 | $\stackrel{\square}{\bullet}$ |
| Theta Steps | 10000 | $\checkmark$ | Density Air (SI Units) | 1.2034 | $\div$ |
| Time0 (Seconds) | 0 | $\checkmark$ | Coefficient of Form | 0.500 | $\div$ |
| Time 1 (Seconds) | 120 | $\stackrel{\square}{*}$ | Wind Speed (Knots) | 0 | $\stackrel{\square}{*}$ |
| Time Steps | 10000 | $\div$ | Wind Direction (Degrees) | 0 | $\div$ |
| Initial Velocity (FPS) | 2500 | $\div$ | $\square$ Vincenty | $\square$ Draw |  |
| Progress |  |  | $\square$ Test | $\square$ Use |  |
| Hrs:Min:Sec.MS | 1 |  | $\square$ Table |  |  |
|  |  |  |  |  |  |

Figure 2 Range Table Generator Form
The theta angles in the preceding user interface are the beginning and ending angles of elevation for the table generation. If Theta $0=$ Theta 1 then the trajectory (path of motion) of the projectile can be graphed. Also, if Theta $0=$ Theta $1=0$ and the Trunnion Height is greater than zero then the rifle can be fired horizontally and the drop of the projectile can be calculated and/or graphed. We illustrate such a case in the next section. If the Target Height is greater than zero there exists two points where the target intersects the trajectory. When Theta $0=$ Theta 1 and Target Height greater than zero we compute both the ascending target and descending target data. Ascending targets could be aircraft in an anti-aircraft fire scenario. When Theta 0 not equal Theta 1 a table of range values in 100 -yard increments beginning with 1000 yards is created. The number of range values to interpolated by angles of elevation is equal to the number of Theta steps. The Vincenty check box option is to include the curvature of the Earth in the calculations [9]. The density of the humid air is defaulted to the value of the pamphlet mentioned in the introduction. We display the meaning of the Test, Use Cf File, and Table check box options in the Experimental Results section. The coefficient of form can be experimented with to see its impact on the experimental results.

## Experimental Results

The first experiment was to compare our results with the pamphlet's range table at very low angles of elevation namely 0 to 1 degrees. Our range table is shown in the following figure. The coefficient of form was 0.5 and the ballistic coefficient 21.09375 . We used 20,000 angle of elevation steps which yielded a table of 20,000 entries to generate the resulting 12 entry range table. We chose Time 1 to be 5 seconds and used 10,000-time steps.

| 4 | A | B | C | D | E | F | G | H | 1 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 1 | Range | Start | Angle | Final | Angle | Time | V1 | Drift | Y-Max |
| 2 | Yards | Degrees | Minutes | Degrees | Minutes | Sec | FPS | Yards | Feet |
| 3 | 1000 | 0 | 26.9 | 0 | 27 | 1.21 | 2454 | 0.2 | 6 |
| 4 | 1100 | 0 | 29.6 | 0 | 30 | 1.33 | 2449 | 0.2 | 7 |
| 5 | 1200 | 0 | 32.3 | 0 | 33 | 1.46 | 2444 | 0.2 | 9 |
| 6 | 1300 | 0 | 35.1 | 0 | 36 | 1.58 | 2440 | 0.3 | 10 |
| 7 | 1400 | 0 | 37.8 | 0 | 38 | 1.7 | 2435 | 0.3 | 12 |
| 8 | 1500 | 0 | 40.6 | 0 | 41 | 1.83 | 2431 | 0.4 | 13 |
| 9 | 1600 | 0 | 43.3 | 0 | 44 | 1.95 | 2426 | 0.4 | 15 |
| 10 | 1700 | 0 | 46.1 | 0 | 47 | 2.07 | 2422 | 0.5 | 17 |
| 11 | 1800 | 0 | 48.9 | 0 | 50 | 2.2 | 2417 | 0.5 | 19 |
| 12 | 1900 | 0 | 51.7 | 0 | 53 | 2.32 | 2413 | 0.6 | 22 |
| 13 | 2000 | 0 | 54.5 | 0 | 56 | 2.45 | 2408 | 0.7 | 24 |
| 14 | 2100 | 0 | 57.2 | 0 | 59 | 2.57 | 2404 | 0.7 | 27 |

Figure 3 Range Table 1000 to 2100 Yards

Next, we display our detailed deviations from the pamphlet's range table at 1,000 to 2,100 yards.

| 4 | A | B | C | D | E | F | G | H | 1 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 1 | Detailed Deviations from Ordnance Pamphlet 770 |  |  |  |  |  |  |  |  |
| 2 | Range | Start | Angle | Final | Angle | Time | V1 | Drift | Y-Max |
| 3 | Yards | Degrees | Minutes | Degrees | Minutes | Sec | FPS | Yards | Feet |
| 4 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| 5 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | _ |
| 6 | 0 | 0 | 0 | 0 | 0 | -0.01 | 1 | 0 | - |
| 7 | 0 | 0 | -0.1 | 0 | 0 | 0 | 0 | 0 | - |
| 8 | 0 | 0 | -0.1 | 0 | 0 | 0 | 1 | 0 | - |
| 9 | 0 | 0 | -0.1 | 0 | 0 | -0.01 | 0 | 0 | 0 |
| 10 | 0 | 0 | 0 | 0 | 0 | 0 | 1 | 0 | - |
| 11 | 0 | 0 | 0 | 0 | 0 | 0 | 1 | 0 | - |
| 12 | 0 | 0 | 0 | 0 | -1 | 0 | 1 | 0.1 | - |
| 13 | 0 | 0 | 0 | 0 | -1 | 0 | 1 | 0 | - |
| 14 | 0 | 0 | 0 | 0 | -1 | 0 | 1 | 0 | 0 |
| 15 | 0 | 0 | 0.1 | 0 | -1 | 0 | 1 | 0.1 | - |

We now show an error summary for the 12 -entry range table. As you can easily detect we are having the most trouble accurately reproducing the drift numbers. We proceed to discuss our drift methodology.

| A | A | B | C | D |
| :---: | :--- | ---: | ---: | ---: |
| 1 | Total | 30 |  |  |
| 2 | Out of | 87 |  |  |
| 3 | \% Error | 34.48 |  |  |
| 4 |  |  |  |  |
| 5 |  | Err Cnt | Avg Abs Dev |  |
| 6 | Range | 0 | 0 |  |
| 7 | Degrees | 0 | 0 |  |
| 8 | Minutes | 4 | 0.1 |  |
| 9 | Degrees | 0 | 0 |  |
| 10 | Minutes | 4 | 1 |  |
| 11 | Time | 2 | 0.01 |  |
| 12 | V1 | 8 | 1 |  |
| 13 | Drift | 12 | 0.028 |  |

Figure 5 Error Summary for 12-Entry Range Table
Column 8 of our reproduction (Column 6 of the pamphlet) was created using Hamilton's drift formula which is Equation (901) on page 113 of Herrmann's book and given below:

$$
D=X\left(1-D^{\prime}\right) \frac{d^{3}}{\mu w}\left(\phi^{0}+\omega^{0}\right) \sec \phi
$$

Where $X$ is the range, the primed $D$ is the drift coefficient, $d$ is the diameter of the projectile, $w$ is the weight, mu is the final twist of the rifling, and the superscripted angles of elevation and fall must be expressed in radians. The pamphlet contains ten test firings of the guns in question using different angles of elevation and initial velocities. Unfortunately, the angle of fall and the drift are not tabulated. We compute the drift coefficient by transposing the preceding equation:

$$
D^{\prime}=1-\frac{D \mu w}{X d^{3}\left(\phi^{0}+\omega^{0}\right)} \cos \phi
$$

The ranges and angles of elevation are known from the test firings. We approximate that the angle of elevation and the angle of fall are the same as in the vacuum case. We use 3 times the mean test firing errors as the drifts. The bore length of the rifle is 800 inches. Mu according to the pamphlet is 800 calibers / $32=25$ calibers. The pamphlet states that for a gun with $\mathrm{mu}=800$ calibers $/ 25=32$ calibers to multiply column 6 by 0.78 which is a rounded version of $25 / 32$. We average the drift coefficients found using the above equation and get a value of 0.82700994 for the drift coefficient.

Now we perform the same experiments for between 4 and 5 degrees elevation. This time we use Time 1 of 20 seconds and the same Theta Steps $(20,000)$ and Time Steps 10,000 . The three tables generated are illustrated on the next page.

| 4 | A | B | C | D | E | F | G | H | 1 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 1 | Range | Start | Angle | Final | Angle | Time | V1 | Drift | Y-Max |
| 2 | Yards | Degrees | Minutes | Degrees | Minutes | Sec | FPS | Yards | Feet |
| 3 | 8200 | 4 | 2.4 | 4 | 28 | 10.66 | 2148 | 12.8 | 457 |
| 4 | 8300 | 4 | 5.7 | 4 | 32 | 10.8 | 2144 | 13.2 | 469 |
| 5 | 8400 | 4 | 9 | 4 | 36 | 10.94 | 2141 | 13.5 | 481 |
| 6 | 8500 | 4 | 12.3 | 4 | 40 | 11.08 | 2137 | 13.9 | 494 |
| 7 | 8600 | 4 | 15.6 | 4 | 44 | 11.22 | 2133 | 14.2 | 507 |
| 8 | 8700 | 4 | 18.9 | 4 | 48 | 11.36 | 2129 | 14.6 | 519 |
| 9 | 8800 | 4 | 22.3 | 4 | 52 | 11.5 | 2125 | 14.9 | 533 |
| 10 | 8900 | 4 | 25.6 | 4 | 56 | 11.65 | 2122 | 15.3 | 546 |
| 11 | 9000 | 4 | 29 | 5 | 0 | 11.79 | 2118 | 15.7 | 559 |
| 12 | 9100 | 4 | 32.3 | 5 | 4 | 11.93 | 2114 | 16.1 | 573 |
| 13 | 9200 | 4 | 35.7 | 5 | 9 | 12.08 | 2110 | 16.5 | 587 |
| 14 | 9300 | 4 | 39.1 | 5 | 13 | 12.22 | 2107 | 16.9 | 601 |
| 15 | 9400 | 4 | 42.5 | 5 | 17 | 12.36 | 2103 | 17.3 | 615 |
| 16 | 9500 | 4 | 45.9 | 5 | 21 | 12.51 | 2099 | 17.7 | 630 |
| 17 | 9600 | 4 | 49.3 | 5 | 25 | 12.65 | 2095 | 18.1 | 644 |
| 18 | 9700 | 4 | 52.7 | 5 | 29 | 12.8 | 2092 | 18.5 | 659 |
| 19 | 9800 | 4 | 56.2 | 5 | 34 | 12.94 | 2088 | 18.9 | 674 |
| 20 | 9900 | 4 | 59.6 | 5 | 38 | 13.09 | 2084 | 19.3 | 689 |

Figure 6 Range Table for 4 to 5 Degrees of Elevation
This time we generate an 18 -entry range table. We are still in the second Mayevski zone of 1800 to 2600 feet per second velocities. That means our drag velocity exponent is less than quadratic at 1.7 instead of 2. Unfortunately, there are no short-range test firings. The number of errors between our results and the pamphlet range table is almost at $50 \%$.

| 4 | A | B | C | D | E | F | G | H | 1 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 1 | Detailed Deviations from Ordnance Pamphlet 770 |  |  |  |  |  |  |  |  |
| 2 | Range | Start | Angle | Final | Angle | Time | V1 | Drift | Y-Max |
| 3 | Yards | Degrees | Minutes | Degrees | Minutes | Sec | FPS | Yards | Feet |
| 4 | 0 | 0 | -0.2 | 0 | 0 | -0.01 | -2 | 1.2 |  |
| 5 | 0 | 0 | -0.2 | 0 | 0 | -0.01 | -2 | 0.8 | - |
| 6 | 0 | 0 | -0.2 | 0 | 0 | -0.01 | -3 | 0.5 | - |
| 7 | 0 | 0 | -0.2 | 0 | 0 | -0.01 | -3 | 0.1 | -3 |
| 8 | 0 | 0 | -0.2 | 0 | 0 | -0.01 | -3 | 0.8 | - |
| 9 | 0 | 0 | -0.2 | 0 | 0 | 0 | -3 | 0.4 | - |
| 10 | 0 | 0 | -0.3 | 0 | 0 | 0 | -3 | 0.1 | _ |
| 11 | 0 | 0 | -0.2 | 0 | 0 | -0.01 | -4 | 0.7 | _ |
| 12 | 0 | 0 | -0.2 | 0 | 0 | 0 | -4 | 0.3 | -2 |
| 13 | 0 | 0 | -0.1 | 0 | 0 | 0 | -4 | 0.9 | _ |
| 14 | 0 | 0 | -0.1 | 0 | 0 | 0 | -4 | 0.5 | _ |
| 15 | 0 | 0 | -0.1 | 0 | 0 | 0 | -5 | 0.1 | - |
| 16 | 0 | 0 | -0.1 | 0 | 0 | 0.01 | -5 | 0.7 | _ |
| 17 | 0 | 0 | -0.1 | 0 | 0 | 0 | -5 | 0.3 | -2 |
| 18 | 0 | 0 | -0.1 | 0 | 0 | 0.01 | -5 | 0.9 | _ |
| 19 | 0 | 0 | -0.1 | 0 | 0 | 0 | -6 | 0.5 | - |
| 20 | 0 | 0 | -0.2 | 0 | 0 | 0.01 | -6 | 0.1 |  |
| 21 | 0 | 0 | -0.2 | 0 | 0 | 0 | -6 | 0.7 | - |

Figure 7 Detailed Deviations from Pamphlet for 4 to 5 Degrees Elevation

|  | A | B | C | D |
| :--- | :--- | ---: | ---: | ---: |
| 1 | Total | 63 |  |  |
| 2 | Out of | 129 |  |  |
| 3 | \% Error | 48.84 |  |  |
| 4 |  |  |  |  |
| 5 |  | Err Cnt | Avg Abs Dev |  |
| 6 | Range | 0 | 0 |  |
| 7 | Degrees | 0 | 0 |  |
| 8 | Minutes | 18 | 0.167 |  |
| 9 | Degrees | 0 | 0 |  |
| 10 | Minutes | 0 | 0 |  |
| 11 | Time | 9 | 0.0 |  |
| 12 | V1 | 18 | 4.056 |  |
| 13 | Drift | 18 | 0.543 |  |
|  |  |  |  |  |

Figure 8 Detailed Deviations from Pamphlet for 4 to 5 Degrees Elevation
We try to duplicate the data in the test firings table of the pamphlet. First, we use a constant coefficient of form of 0.5 . The results are displayed in the following figure.

| 4 | A | B | c | D | E | F | G | H | 1 | J | K |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 1 | A | B | C | D | E | F | G | H | 1 | J K | K |
| 2 | Init | Vo | Range | Corr1 | Range | Corr2 | Range | Range | \% Error | \% Error | \% Error |
| 3 | Angle | FPS | Yards | Yards | Yards | Yards | Yards | Real | C \& H | E \& H | G \& H |
| 4 | 10 | 2502 | 17734 | -104 | 17630 | -104 | 17630 | 17402 | 1.9092 | 1.312 | 1.3105 |
| 5 | 15 | 2502 | 24100 | -118 | 23982 | -118 | 23981 | 23642 | 1.9352 | 1.4361 | 1.4344 |
| 6 | 25 | 2500 | 33655 | -124 | 33531 | -124 | 33530 | 32971 | 2.0744 | 1.6987 | 1.6969 |
| 7 | 45 | 2500 | 43201 | -101 | 43099 | -102 | 43099 | 42643 | 1.3077 | 1.0702 | 1.0687 |
| 8 | 15 | 2478 | 23733 | -115 | 23618 | -115 | 23618 | 23182 | 2.377 | 1.8824 | 1.8807 |
| 9 | 20 | 2476 | 28852 | -119 | 28733 | -120 | 28732 | 28110 | 2.6392 | 2.2157 | 2.2139 |
| 10 | 25 | 2481 | 33249 | -121 | 33128 | -122 | 33127 | 32544 | 2.1665 | 1.7941 | 1.7923 |
| 11 | 30 | 2475 | 36688 | -120 | 36569 | -120 | 36568 | 36539 | 0.4081 | 0.0809 | 0.0791 |
| 12 | 45 | 2475 | 42462 | -98 | 42364 | -99 | 42364 | 43188 | 1.6804 | 1.9072 | 1.9086 |
| 13 | 15 | 2439 | 23138 | -109 | 23029 | -110 | 23028 | 23028 | 0.4777 | 0.0029 | 0.0014 |

Figure 9 Test Firings Comparison Constant Coefficients of Form
Columns $A$ and $H$ are taken from the test firings table in the pamphlet. Column $D$ is the curvature of the Earth correction using the formula given in Herrmann. The column F is Vincenty formulas correction for the curvature or Earth or the great circle distance correction. Remember on a sphere the shortest distance between two points is a geodesic not a straight line. Columns I-J are percentage errors between our values and the pamphlet's test firing table. The percentage error is defined as 100 * |experimental value - true value | / | true value|. We take the pamphlet's values as the true values. We now repeat the same experiment using five different values of the coefficient of form, one for each initial velocity zone.

| 4 | A | B | C | D | E | F | G | H | 1 | J | K |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 1 | A | B | C | D | E | F | G | H | 1 | J K | K |
| 2 | Init | Vo | Range | Corr1 | Range | Corr2 | Range | Range | \% Error | \% Error | \% Error |
| 3 | Angle | FPS | Yards | Yards | Yards | Yards | Yards | Real | C \& H | E \& H | G \& H |
| 4 | 10 | 2502 | 17480 | -100 | 17380 | -100 | 17380 | 17402 | 0.4461 | 0.1269 | 0.1283 |
| 5 | 15 | 2502 | 23638 | -111 | 23527 | -112 | 23527 | 23642 | 0.0161 | 0.4867 | 0.4883 |
| 6 | 25 | 2500 | 33080 | -118 | 32962 | -119 | 32961 | 32971 | 0.3299 | 0.0286 | 0.0303 |
| 7 | 45 | 2500 | 42401 | -96 | 42305 | -97 | 42304 | 42643 | 0.5665 | 0.7926 | 0.794 |
| 8 | 15 | 2478 | 23177 | -107 | 23071 | -107 | 23070 | 23182 | 0.0195 | 0.4799 | 0.4814 |
| 9 | 20 | 2476 | 28066 | -110 | 27956 | -111 | 27956 | 28110 | 0.1552 | 0.5472 | 0.5487 |
| 10 | 25 | 2481 | 32280 | -112 | 32168 | -112 | 32168 | 32544 | 0.8114 | 1.1552 | 1.1568 |
| 11 | 30 | 2475 | 36794 | -120 | 36673 | -121 | 36673 | 36539 | 0.6968 | 0.3671 | 0.3654 |
| 12 | 45 | 2475 | 42586 | -99 | 42488 | -99 | 42487 | 43188 | 1.3928 | 1.6214 | 1.6228 |
| 13 | 15 | 2439 | 23011 | -108 | 22904 | -108 | 22903 | 23028 | 0.0736 | 0.5406 | 0.5422 |

Figure 10 Test Firing Comparison Variable Coefficients of Form
Next, we display the coefficients of form utilized and the corresponding ballistic coefficients.

|  | A | B | C | D | E |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 1 | Coefficients of Form for Each Initial | Velocity Zone |  |  |  |
| 2 |  |  |  |  |  |
| 3 | V0 | 2502 | 0.538038 |  |  |
| 4 | V0 | 2500 | 0.526946 |  |  |
| 5 | V0 | 2476 | 0.547196 |  |  |
| 6 | V0 | 2475 | 0.49574 |  |  |
| 7 | V0 | 2439 | 0.510899 |  |  |
| 8 |  |  |  |  |  |
| 9 | Ballistic Coefficients for Each Initial Velocity Zone |  |  |  |  |
| 10 |  |  |  |  |  |
| 11 | V0 | 2502 | 19.60249 |  |  |
| 12 | V0 | 2500 | 20.01511 |  |  |
| 13 | V0 | 2476 | 19.2744 |  |  |
| 14 | V0 | 2475 | 21.27503 |  |  |
| 15 | V0 | 2439 | 20.64378 |  |  |

Figure 11 Coefficients of Form Etc.
A word about the generation of the variable coefficients of form. We utilized an evolutionary hill climber to determine the coefficients. We used the sum of the percentage differences between the uncorrected range and pamphlet's range for each initial velocity zone as the fitness to be minimized. The hill climber used tournament selection with a tournament size of two. After each mutation of one of the five potential coefficients of form, we would replace the worst individual in the population. Therefore, the hill climber is elitist in nature.

As a final pamphlet related test, we look at angles of elevation form 5 degrees to the maximum elevation of 45 degrees in 5 -degree steps. The results illustrated next.


Figure 12 Range Table Comparison 5 to 45 Degrees
Just for the fun of it consider the following scenario. Suppose you had a 16"/50 caliber naval artillery gun on a 32 -foot trunnion overlooking the English Channel on Dover Cliffs ( 300 feet above sea level). Now we simulate the firing of the rifle. The projectile drops 332 feet in 3,699.23 yards or 2.1018 miles. The time of flight would be 4.595 seconds. See the accompanying figures. The angle of elevation was, of course, 0 degrees. Now suppose France is 20 miles away. We crank the elevation to 27 degrees and the AP projectile carries $35,468.95$ yards or 20.1528 miles reaching an apogee (summit) of $16,230.65$ feet or 3.0740 miles and the time of flight is 63.192 seconds. Raise the elevation to 45 degrees and the projectile goes $43,444.67$ yards or 24.6850 miles reaching an apogee of $37,488.62$ feet or 7.1001 miles and the time of flight is 96.348 seconds.


Figure 13 Firing from the Cliffs of Dover into the Straits


Figure 14 Message Box from Draw Option of Our Application

## Conclusions

Although our efforts at exactly duplicating the results of the pamphlet did not come to fruition, we did come relatively close to the 1941 results. We had the distinct advantage of using a modern digital computer with all computations in double precision. Our double precision means 15 to 17 digits of significance. Back in the day, I am sure this would be considered an exciting amount of precision. The electromechanical analog computers in the early 1940s epoch must have had not many digits of precision. Manufacturing tolerances were just not that tight in that bygone but certainly not forgotten era. I suspect that the actual numerical integration of the 1940s computation was done using the Adams-BashforthMoulton predictor-corrector algorithm and not the Runge-Kutta or Siacci methods. The relative agreement between our numbers and the pamphlet's data at low angles of elevation is certainly satisfying from our perspective.

In the future, we will look deeper into the discrepancies between our results and those of the pamphlet. Also, we will publish our Siacci method experiments at low elevations of 0 to 10 degrees elevation.

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