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1  /*
2  * Other online mathematics problems (c)
3  * August 27, 2024 by James Pate Williams, Jr.
4  * Find the root of  $f(t) = \cos(2t) + \sin(3t)$ 
5  *  $t = 0.628318530718$ 
6  *  $f(t) = 1.11022302e-16$ 
7  * Also find the roots of the equations
8  *  $f(x) = \sqrt{1 + \sqrt{1 + x}} - x^{1/3}$ 
9  *  $x = 8.000000000000$ 
10 *  $f(x) = 0.00000000e+00$ 
11 * Solution of  $f(x) = 9^x + 12^x - 16^x$ 
12 *  $x = -16.387968065352$ 
13 *  $f(x) = 2.32137533e-16$ 
14 * Solution of  $f(x) = 8^x - 2^x - 2(6^x - 3^x)$ 
15 *  $x = 1.000000000000$ 
16 *  $f(x) = 0.00000000e+00$ 
17 * Solution of  $f(a,x)=\sin(\sqrt{ax-x^2})=0$ 
18 * Subject to the constraint  $x+y=100$ 
19 * Where  $x$  and  $y$  are the two roots of
20 *  $g(a,x)=ax-x^2-n*n*\pi*\pi=0$  and  $n=15$ 
21 * Solve for a real root of the equation
22 *  $f(x)=\log_6(5+x)+\log_6(x)=0$ 
23 */
24
25 #include <math.h>
26 #include <stdio.h>
27 #include <stdlib.h>
28 #include <time.h>
29
30 typedef long double real;
31
32 real f1(real t) {
33     return cosl(2 * t) + cosl(3 * t);
34 }
35
36 real g(real t) {
37     return -2 * sinl(2 * t) - 3 * sinl(3 * t);
38 }
39
40 real f2(real x) {
41     return sqrtl(1 + sqrtl(1 + x)) - powl(x, 1.0 / 3.0);
42 }
43
44 real f3(real x) {
45     return powl(9, x) + powl(12, x) - powl(16, x);
46 }
47
48 real f4(real x) {
49     return powl(8, x) - powl(2, x) -
50         2 * (powl(6, x) - powl(3, x));
51 }
52

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53 real CentralDifference(  
54     real x, real h, real(*fx)(real)) {  
55     return (fx(x + h) - fx(x - h)) / (2.0 * h);  
56 }  
57  
58 real NewtonRaphson1(  
59     real x0, real ftolerance, real xtolerance,  
60     real(*fx)(real), real(*deriv)(real)) {  
61     real x1 = 0.0;  
62     while (1) {  
63         real f = fx(x0);  
64         real dfdx = deriv(x0);  
65         x1 = x0 - f / dfdx;  
66         if (fabsl(x1 - x0) < xtolerance ||  
67             fabsl(f) < ftolerance)  
68             break;  
69         x0 = x1;  
70     }  
71     return x1;  
72 }  
73  
74 real NewtonRaphson2(  
75     real x0, real ftolerance, real xtolerance,  
76     real(*fx)(real),  
77     real(*deriv)(real, real, real(*fx)(real))) {  
78     real h = 2.0 / 10000.0, x1 = 0.0;  
79     while (1) {  
80         real f = fx(x0);  
81         real dfdx = deriv(x0, h, fx);  
82         x1 = x0 - f / dfdx;  
83         if (fabsl(x1 - x0) < xtolerance ||  
84             fabsl(f) < ftolerance)  
85             break;  
86         x0 = x1;  
87     }  
88     return x1;  
89 }  
90  
91 void QuadraticEquation(  
92     real a, real b, real c,  
93     real* x, real* y) {  
94     real d = b * b - 4 * a * c;  
95     if (d >= 0) {  
96         *x = (-b + sqrtl(d)) / (2.0 * a);  
97         *y = (-b - sqrtl(d)) / (2.0 * a);  
98     }  
99     else  
100         *x = *y = 0.0;  
101 }  
102  
103 real f5(real a, real x) {  
104     return sinl(sqrtl(a * x - x * x));
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105 }
106
107 real f6(int n, real a, real x) {
108     real pi = 4.0 * atanl(1.0);
109     return a * x - x * x - (real)n * n * pi * pi;
110 }
111
112 real f7(int n, real a, real x) {
113     return sqrt(f6(n, a, x));
114 }
115
116 void HillClimber(
117     int n, int population, int generation,
118     int seed, real* a, real* f, real* x,
119     real* y) {
120     int g = 0, i = 0, j = 0;
121     int* index = (int*)calloc(
122         population, sizeof(int));
123     real bestFitness = 1.0e16;
124     real childa = 0, childx = 0, childy = 0;
125     real pi = 4.0 * atanl(1.0);
126     real* fitness = (real*)calloc(
127         population, sizeof(real));
128     real** gene = (real**)calloc(
129         population, sizeof(real*));
130     if (fitness == NULL)
131         exit(-1);
132     if (gene == NULL)
133         exit(-2);
134     for (i = 0; i < population; i++) {
135         gene[i] = (real*)calloc(3, sizeof(real));
136         if (gene[i] == NULL)
137             exit(-3);
138     }
139     for (i = 0; i < population; i++) {
140         childa = gene[i][0] = 112.0 * (real)rand() / RAND_MAX;
141         QuadraticEquation(
142             -1.0, childa, -(real)n * n * pi * pi,
143             &childx, &childy);
144         fitness[i] = f6(n, childa, childx);
145         gene[i][1] = childx;
146         gene[i][2] = childy;
147         *a = childa;
148         *x = childx;
149         *y = childy;
150     }
151     for (g = 1; g <= generation; g++) {
152         int count = 0;
153         int parent1 = rand() % population;
154         int parent2 = rand() % population;
155         int parentc = parent1 < parent2 ?
156             parent1 : parent2;
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157     real maximum = fitness[0];
158     childa = gene[parentc][0] + 0.0001;
159     QuadraticEquation(
160         -1.0, childa, -(real)n * n * pi * pi,
161         &childx, &childy);
162     real childf = f6(n, childa, childx);
163     for (i = 1; i < population; i++)
164         if (fitness[i] > maximum)
165             maximum = fitness[i];
166     for (i = 0; i < population; i++)
167         if (fitness[i] == maximum)
168             index[count++] = i;
169     if (childf < fitness[index[rand() % count]]) {
170         gene[parentc][0] = childa;
171         gene[parentc][1] = childx;
172         gene[parentc][2] = childy;
173         fitness[parentc] = childf;
174     }
175     if (childf < bestFitness &&
176         childf >= 0.0) {
177         *a = childa;
178         *x = childx;
179         *y = childy;
180         *f = childf;
181         bestFitness = childf;
182     }
183 }
184 }
185
186 real log6l(real x) {
187     return log10l(x) / log10l(6.0);
188 }
189
190 real f8(real x) {
191     return log6l(5 + x) + log6l(x);
192 }
193
194 real f9(real x) {
195     return 1.0 / (5 + x) + 1.0 / x;
196 }
197
198 int main(void) {
199     int n = 15, population = 25, generation = 100000000, seed = 1;
200     clock_t time0 = 0, time1 = 0;
201     real runtime = 0;
202     real ftolerance = 1.0e-15, xtolerance = 1.0e-15;
203     real a = 0, f = 0, t = 0, x = 0, y = 0;
204     t = NewtonRaphson1(
205         0.5, ftolerance, xtolerance, f1, g);
206     printf_s("Solution of f(t) = cos(2t) + cos(3t)\n");
207     printf_s("t      = %t%14.12Lf\n", t);
208     printf_s("f(t) = %t%14.8e\n", f1(t));
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209     x = NewtonRaphson2(
210         1.5, ftolerance, xtolerance, f2, CentralDifference);
211     printf_s("Solution of  $f(x) = \sqrt{1 + \sqrt{1 + x}} - x^{1/3}$ \n");
212     printf_s("x      = %14.12Lf\n", x);
213     printf_s("f(x) = %14.8e\n", f2(x));
214     x = NewtonRaphson2(
215         1.0, ftolerance, xtolerance, f3, CentralDifference);
216     printf_s("Solution of  $f(x) = 9^x + 12^x - 16^x$ \n");
217     printf_s("x      = %14.12Lf\n", x);
218     printf_s("f(x) = %14.8e\n", f3(x));
219     x = NewtonRaphson2(
220         1.0, ftolerance, xtolerance, f4, CentralDifference);
221     printf_s("Solution of  $f(x) = 8^x - 2^x - 2(6^x - 3^x)$ \n");
222     printf_s("x      = %14.12Lf\n", x);
223     printf_s("f(x) = %14.8e\n", f4(x));
224     printf_s("Solution of  $f(a,x)=\sin(\sqrt{ax-x^2})=0$ \n");
225     printf_s("Subject to the constraint  $x+y=100$ \n");
226     printf_s("Where x and y are the two roots of\n");
227     printf_s(" $g(a,x)=ax-x^2-n*\pi*pi=0$ \n");
228     printf_s("and  $n=%d$ \n", n);
229     time0 = clock();
230     HillClimber(n, population, generation, seed, &a, &f, &x, &y);
231     time1 = clock();
232     runtime = ((real)time1 - time0) / CLOCKS_PER_SEC;
233     printf_s("a = %15.12Lf\n", a);
234     printf_s("x = %15.12Lf\n", x);
235     printf_s("y = %15.12Lf\n", y);
236     printf_s("g = %15.12Lf\n", f);
237     printf_s("s = %15.12Lf\n", x + y);
238     printf_s("runtime in seconds = %Lf\n", runtime);
239     printf_s("Solve for a real root of the equation\n");
240     printf_s(" $f(x)=\log_6(5+x)+\log_6(x)=0$ \n");
241     printf_s("First we test our  $\log_6(x)$  function\n");
242     printf_s("log6(12) = %Lf\n", log6(12));
243     printf_s("log6(36) = %Lf\n", log6(36));
244     x = NewtonRaphson1(
245         0.5, ftolerance, xtolerance, f8, f9);
246     printf_s("x = %12.10Lf\n", x);
247     printf_s("f = %12.10Lf\n", f8(x));
248     return 0;
249 }

```