

1. Simplify

$$\begin{aligned} (\vec{A} \times \vec{B}) \cdot \vec{C} &= \varepsilon_{ijk} A_i B_j C_k = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ A_x & A_y & A_z \\ B_x & B_y & B_z \end{vmatrix} \begin{vmatrix} \hat{i} & \hat{j} \\ B_x & B_y \end{vmatrix} \cdot \vec{C} \\ &= [(A_y B_z - A_z B_y)\hat{i} + (A_z B_x - A_x B_z)\hat{j} + (A_x B_y - A_y B_x)\hat{k}] \cdot \vec{C} \\ &= (A_y B_z - A_z B_y)C_x + (A_z B_x - A_x B_z)C_y + (A_x B_y - A_y B_x)C_z \end{aligned}$$

2. Simplify

$$\begin{aligned} (\vec{A} \times \vec{B}) \cdot (\vec{C} \times \vec{D}) &= \varepsilon_{ijk} A_i B_j \hat{e}_k \varepsilon_{lmn} C_l D_m \hat{e}_n = \varepsilon_{ijk} A_i B_j \varepsilon_{lmk} C_l D_m \\ &= \varepsilon_{ijk} \varepsilon_{lmk} A_i B_j C_l D_m = (\delta_{il} \delta_{jm} - \delta_{im} \delta_{jl}) A_i B_j C_l D_m \\ &= A_i B_j C_i D_j - A_i B_j C_j D_i = A_i B_j (C_i D_j - C_j D_i) \end{aligned}$$

3. Simplify

$$(\vec{A} \times \vec{B}) \cdot (\vec{B} \times \vec{C}) \times (\vec{C} \times \vec{A})$$

First, we need to compute the second and third factors:

$$\begin{aligned} (\vec{B} \times \vec{C}) \times (\vec{C} \times \vec{A}) &= \varepsilon_{ijk} B_i C_j \hat{e}_k \varepsilon_{lmn} C_l A_m \hat{e}_n \\ \vec{B} \times \vec{C} &= \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ B_x & B_y & B_z \\ C_x & C_y & C_z \end{vmatrix} \begin{vmatrix} \hat{i} & \hat{j} \\ C_x & C_y \end{vmatrix} \\ &= (B_y C_z - B_z C_y)\hat{i} + (B_z C_x - B_x C_z)\hat{j} + (B_x C_y - B_y C_x)\hat{k} \\ \vec{C} \times \vec{A} &= \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ C_x & C_y & C_z \\ A_x & A_y & A_z \end{vmatrix} \begin{vmatrix} \hat{i} & \hat{j} \\ A_x & A_y \end{vmatrix} \\ &= (C_y A_z - C_z A_y)\hat{i} + (C_z A_x - C_x A_z)\hat{j} + (C_x A_y - C_y A_x)\hat{k} \\ (\vec{B} \times \vec{C}) \times (\vec{C} \times \vec{A}) &= \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ B_y C_z - B_z C_y & B_z C_x - B_x C_z & B_x C_y - B_y C_x \\ C_y A_z - C_z A_y & C_z A_x - C_x A_z & C_x A_y - C_y A_x \end{vmatrix} \begin{vmatrix} \hat{i} & \hat{j} \\ C_y A_z - C_z A_y & C_z A_x - C_x A_z \end{vmatrix} \end{aligned}$$

Like any good computer scientist and software engineer, I will write Win32 C/C++ console application to verify my formulas.

Exercise 1 (a) 30
Exercise 1 (b) -13
Exercise 1 (c) 5
Exercise 1 (d) 1

Exercise 2	5		
Exercise 3	0		
Exercise 4	0.666667		
Exercise 5	1		
Exercise 10	0.648886	0.648886	

D:\VectorAnalysis\x64\Debug\VectorAnalysis.exe (process 12500)
exited with code 0 (0x0).
Press any key to close this window . . .